

# Minimax Predictive Densities of Dynamic Linear Model under Kullback-Leibler Loss

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Consider a time series  $(y_t, \mathbf{x}_t)$ , where  $y_t \in \mathbb{R}$  and  $\mathbf{x}_t$  is a countably infinite vector. Assume that the data generating process of  $y_t$  can be represented as a dynamic linear models:

$$y_t = \mu_t + \sum_{i=1}^{\infty} \beta_i x_{i,t}$$

$x_{i,t}$ ; Markov processes,

where  $\mu_t$  is the drift. Observed processes are  $\{y_t\}$  and  $\{x_{i,t}\}_{i \in I}$  where  $I$  is an arbitrary set of finite  $i$ . Set  $\mathcal{F}_t = \sigma(y_s, x_{i,s}; s \leq t, i \in I)$ , the smallest  $\sigma$ -algebra that makes all of the observable processes measurable.

Based on the information  $\mathcal{F}_t$ , we consider the problem of obtaining a predictive density  $\hat{p}(y_{t+1} | \mathcal{F}_t)$  for  $y_{t+1}$  that is close to  $p(y_{t+1})$ . We measure this closeness by Kullback–Leibler (KL) loss,

$$L(p, \hat{p}(\cdot | \mathcal{F}_t)) = \int \log \frac{p(y_{t+1})}{\hat{p}(y_{t+1} | \mathcal{F}_t)} p(y_{t+1}) dy_{t+1}$$

and evaluate  $\hat{p}$  by its expected loss or risk function

$$R_{KL}(p, \hat{p}) = \int L(p, \hat{p}(\cdot | \mathcal{F}_t)) d\mu_{Y,X}$$

where  $\mu_{Y,X}$  is cylindrical measure for  $\{y_s, x_s\}_{0 \leq s \leq t}$ .

We construct a predictive density by dynamic linear model(DLM), that is,

$$\begin{aligned} y_t &= F_t^\top \boldsymbol{\theta}_t + v_t, & v_t &\sim \mathcal{N}(0, V_t) \\ \boldsymbol{\theta}_t &= G_t^\top \boldsymbol{\theta}_{t-1} + \mathbf{w}_t, & \mathbf{w}_t &\sim \mathcal{N}(0, W_t) \end{aligned}$$

where  $F_t = [1, x_{1,t}, \dots, x_{I,t}]^\top$ ,  $\boldsymbol{\theta}_t = [\theta_{0,t}, \dots, \theta_{I,t}]^\top$  is  $(1 + I)$  vector,  $G_t$  is known matrix,  $V_t$  is known scalar, and  $W_t$  is known matrix. Our purpose is to show that when  $G_t = I$ , random walk DLM, the predictive density has minimaxity with respect to KL divergence loss.

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